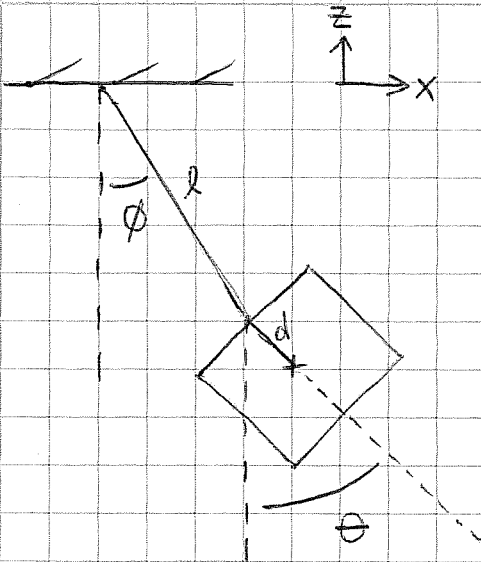


$$\frac{\partial \mathcal{L}}{\partial x_i} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}_i} = 0$$

$$\mathcal{L} = T - U$$



$$x = l \sin \phi + d \sin \theta$$

$$z = -l \cos \phi - d \cos \theta$$

$$\dot{x} = l \dot{\phi} \cos \phi + d \dot{\theta} \cos \theta$$

$$\dot{z} = l \dot{\phi} \sin \phi + d \dot{\theta} \sin \theta$$

$$I = I_{cm} + md^2$$

$$T = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} m \dot{z}^2 + \frac{1}{2} I \dot{\theta}^2$$

$$= \frac{1}{2} m (l^2 \dot{\phi}^2 \cos^2 \phi + d^2 \dot{\theta}^2 \cos^2 \theta + 2 l \dot{\phi} d \dot{\theta} \cos \phi \cos \theta)$$

$$+ \frac{1}{2} m (l^2 \dot{\phi}^2 \sin^2 \phi + d^2 \dot{\theta}^2 \sin^2 \theta + 2 l \dot{\phi} d \dot{\theta} \sin \phi \sin \theta)$$

$$+ \frac{1}{2} I_{cm} \dot{\theta}^2 + \frac{1}{2} m d^2 \dot{\theta}^2$$

$$= \frac{1}{2} m l^2 \dot{\phi}^2 + \frac{1}{2} m d^2 \dot{\theta}^2 + m l d \dot{\phi} \dot{\theta} (\cos \phi \cos \theta + \sin \phi \sin \theta)$$

$$+ \frac{1}{2} I_{cm} \dot{\theta}^2 + \frac{1}{2} m d^2 \dot{\theta}^2$$

$$= \frac{1}{2} m l^2 \dot{\phi}^2 + m d^2 \dot{\theta}^2 + m l d \dot{\phi} \dot{\theta} \cos(\phi - \theta) + \frac{1}{2} I_{cm} \dot{\theta}^2$$

$$U = mgz$$

$$= -mg(l \cos \phi + d \cos \theta)$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\phi}} = m l^2 \dot{\phi} + m l d \dot{\theta} \cos(\phi - \theta)$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = m l^2 \ddot{\phi} + m l d \ddot{\theta} \cos(\phi - \theta) - m l d \dot{\theta} (\dot{\phi} - \dot{\theta}) \sin(\phi - \theta)$$

$$\frac{\partial \mathcal{L}}{\partial \phi} = -m l d \dot{\phi} \dot{\theta} \sin(\phi - \theta)$$

$$\Rightarrow -m l d \dot{\phi} \dot{\theta} \sin(\phi - \theta) - m l^2 \ddot{\phi} - m l d \ddot{\theta} \cos(\phi - \theta) + m l d \dot{\theta} (\dot{\phi} - \dot{\theta}) \sin(\phi - \theta)$$

$$\Rightarrow -m l^2 \ddot{\phi} - m l d \ddot{\theta} \cos(\phi - \theta) - m l d \dot{\theta}^2 \sin(\phi - \theta) = 0$$