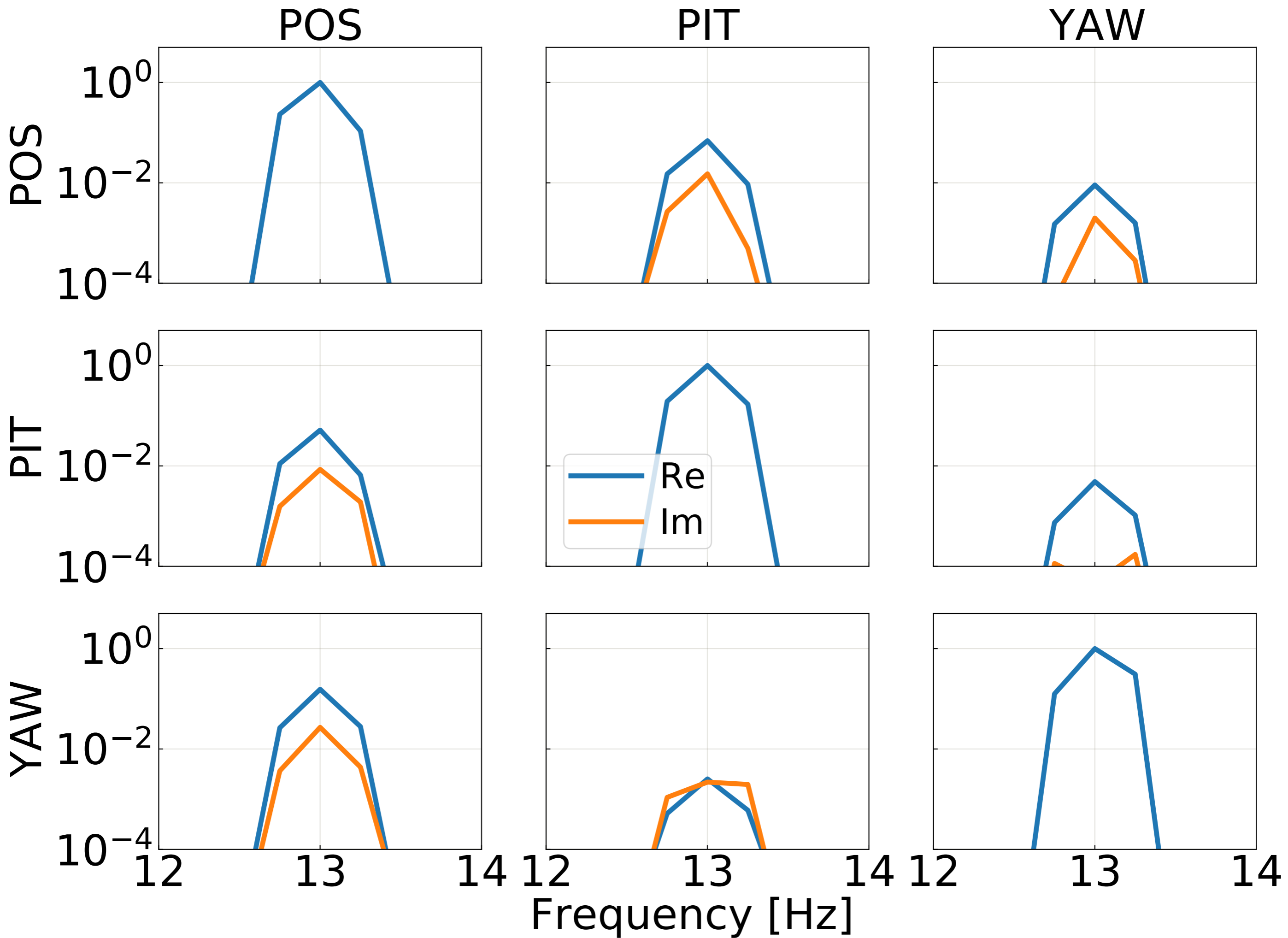


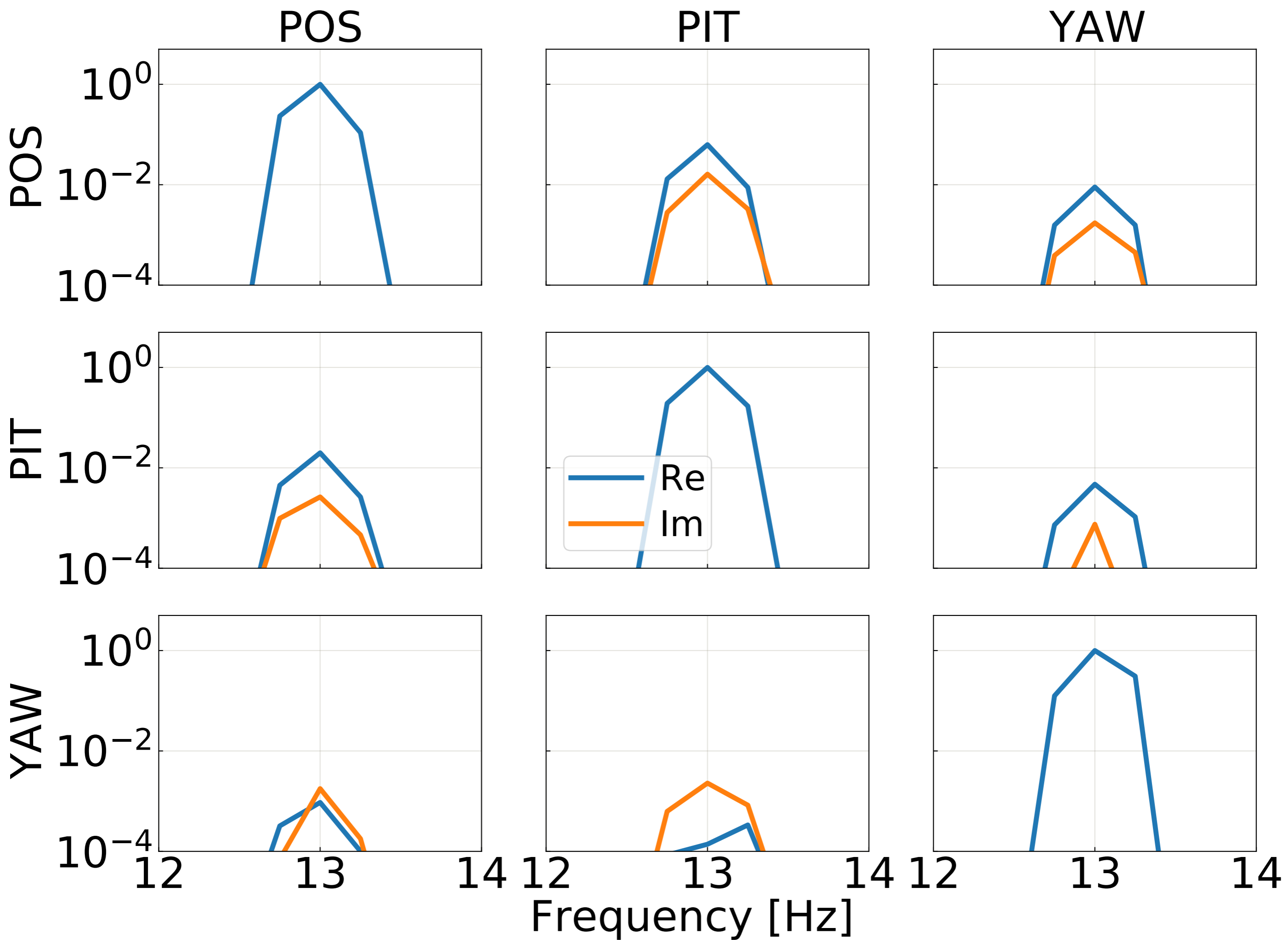
# TF estimates between different DOFs.

Iteration: 0 ; Col: Excited DOF ; Row: Sensed DOF



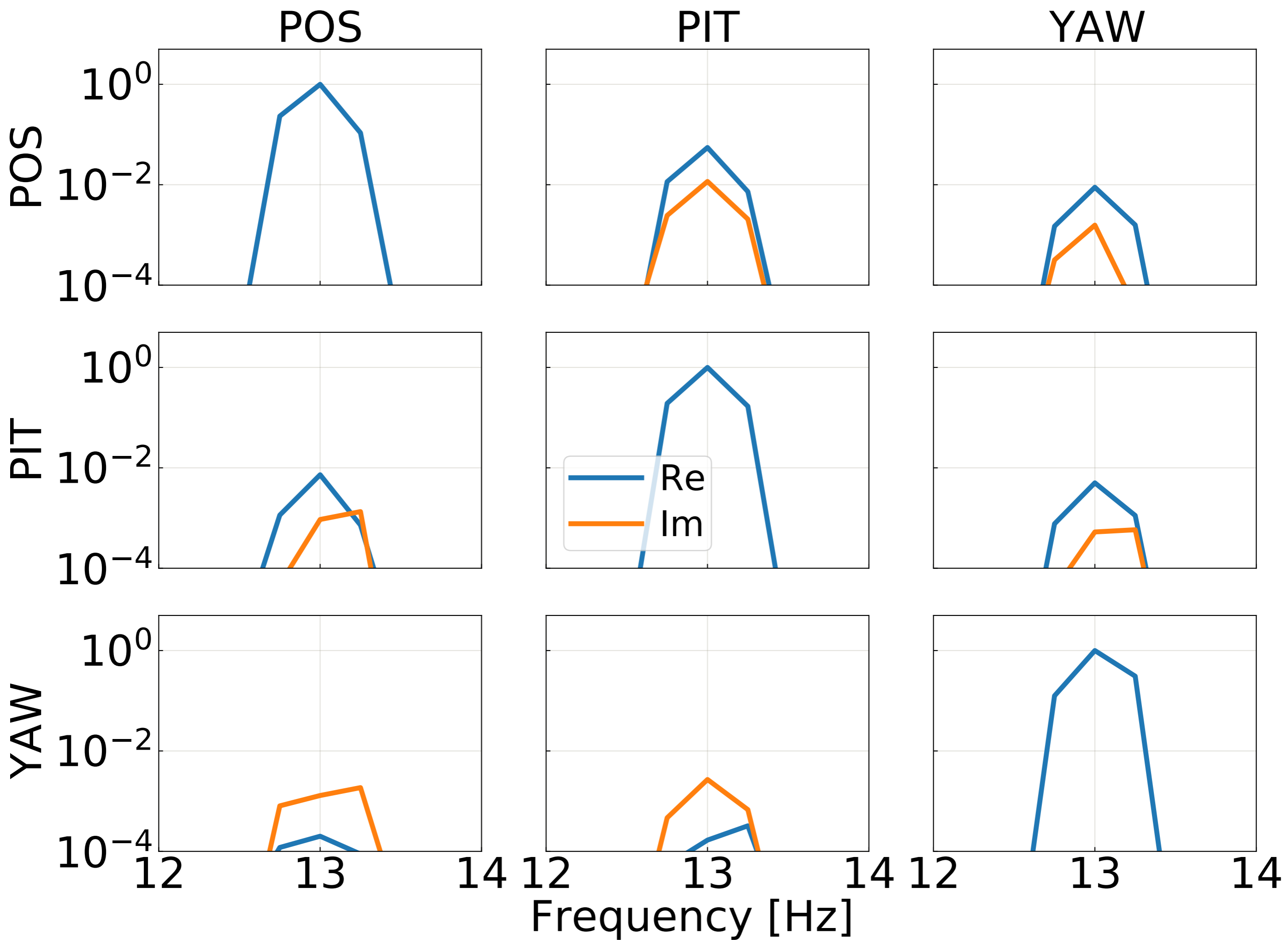
# TF estimates between different DOFs.

Iteration: 7 ; Col: Excited DOF ; Row: Sensed DOF



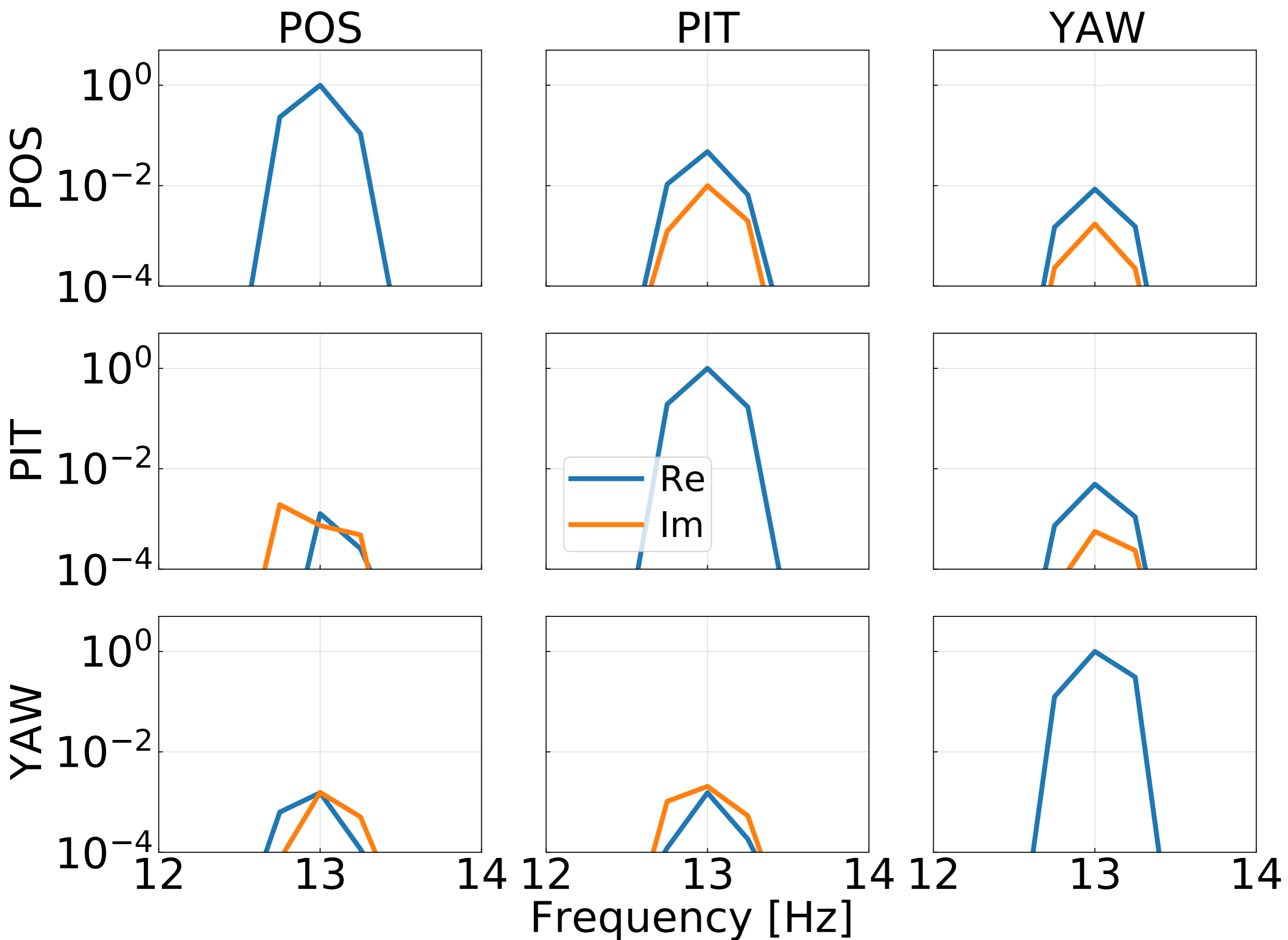
# TF estimates between different DOFs.

Iteration: 14 ; Col: Excited DOF ; Row: Sensed DOF



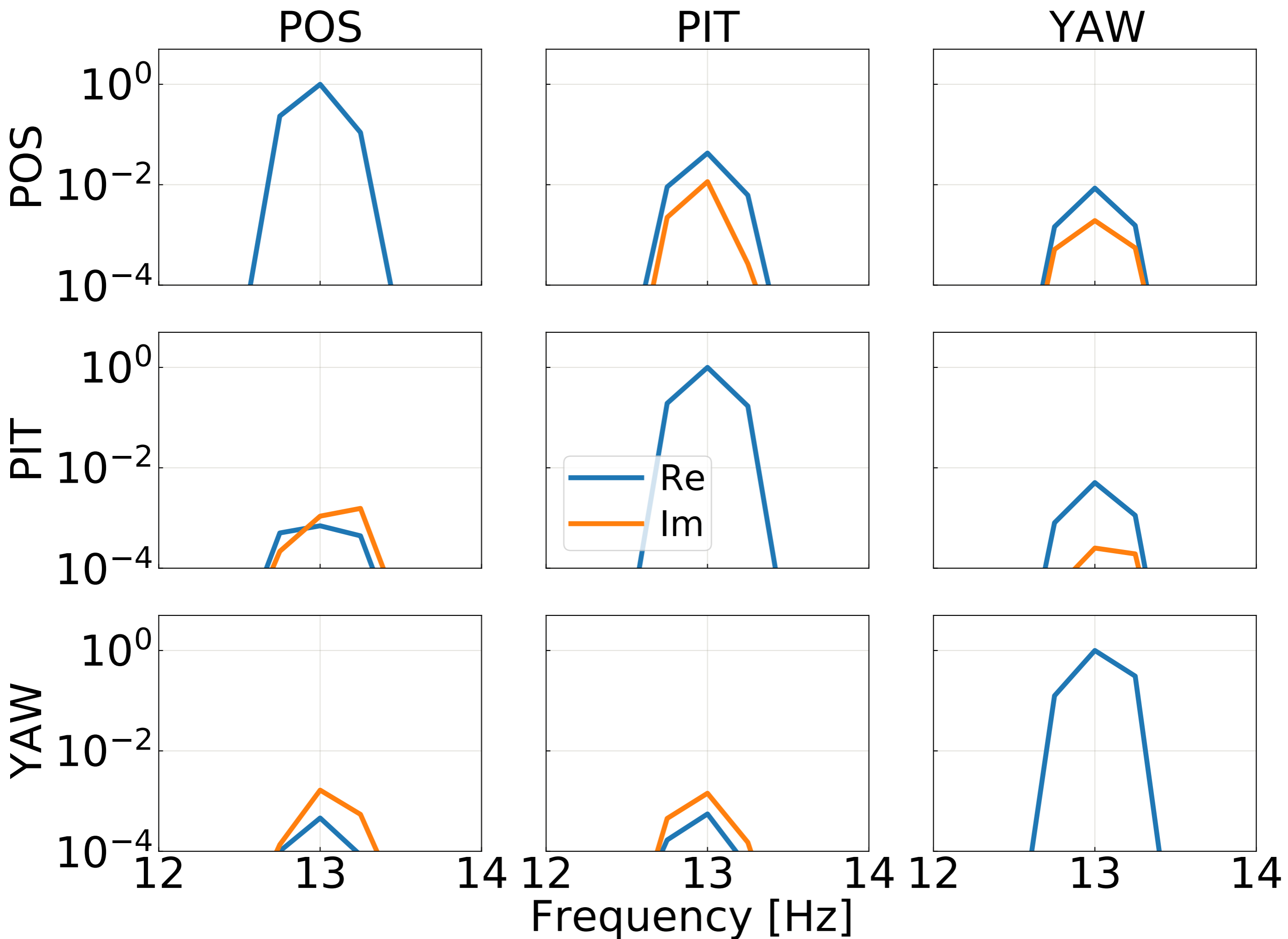
# TF estimates between different DOFs.

Iteration: 21 ; Col: Excited DOF ; Row: Sensed DOF



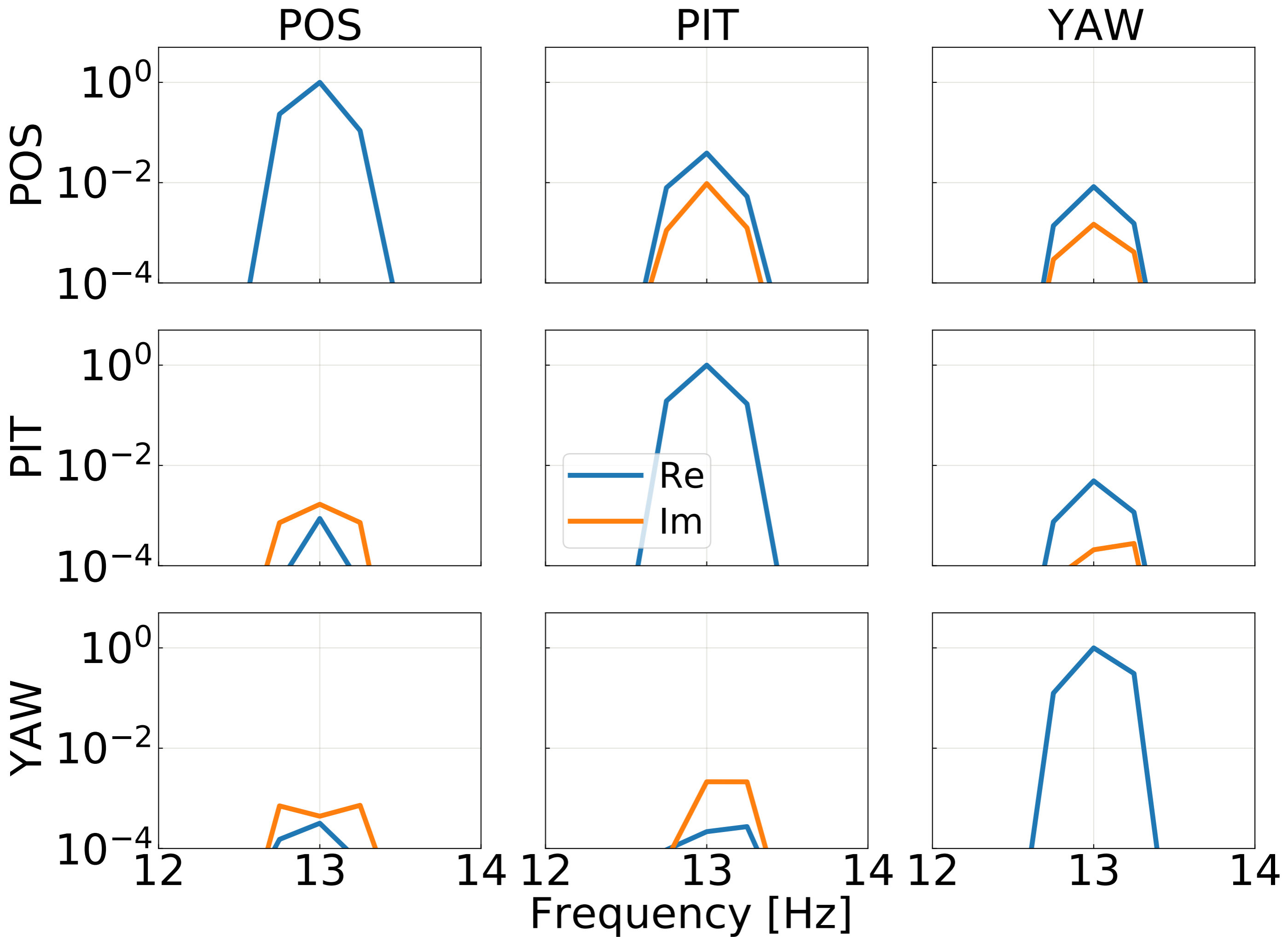
# TF estimates between different DOFs.

Iteration: 28 ; Col: Excited DOF ; Row: Sensed DOF



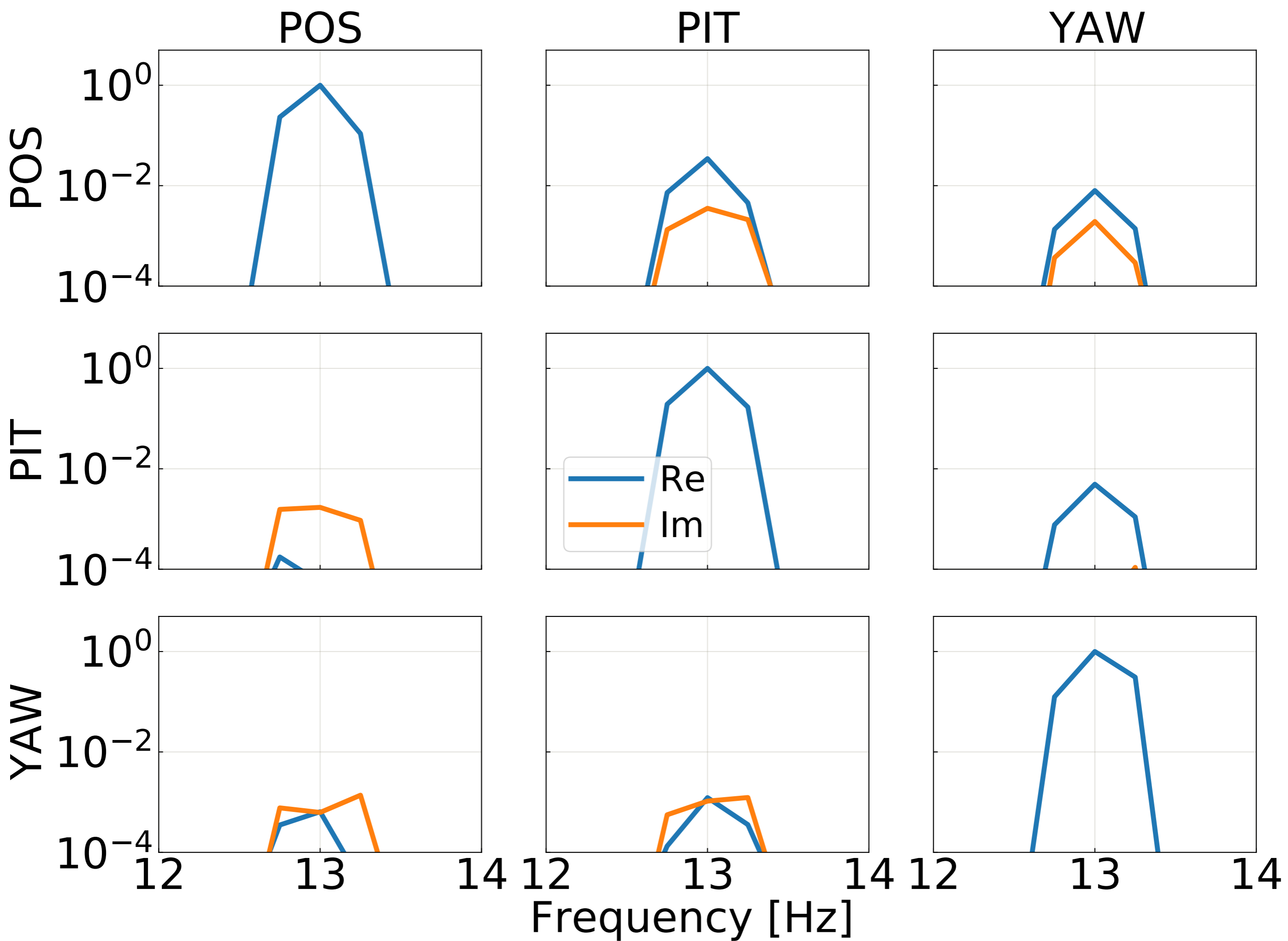
# TF estimates between different DOFs.

Iteration: 35 ; Col: Excited DOF ; Row: Sensed DOF



# TF estimates between different DOFs.

Iteration: 42 ; Col: Excited DOF ; Row: Sensed DOF



# TF estimates between different DOFs.

Iteration: 49 ; Col: Excited DOF ; Row: Sensed DOF

