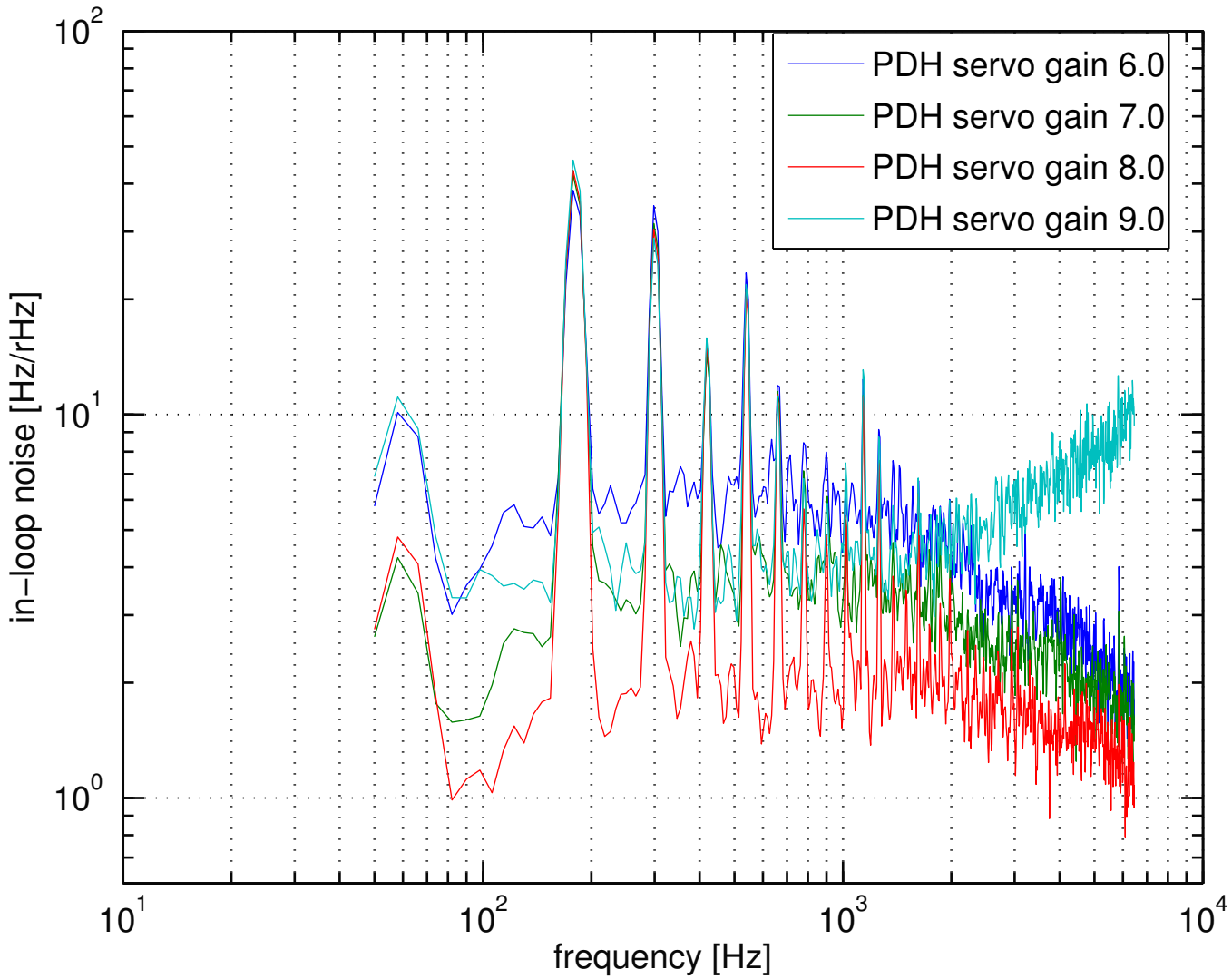
PDH servo gain 6.0
PDH servo gain 7.0
PDH servo gain 8.0
PDH servo gain 9.0
in−loop noise [Hz/rHz]
frequency [Hz]
10^2
10^1
10^0
10^1
10^2
10^3
10^4